Language-Driven 3D Stylization

CSCI-677: Advanced Computer Vision
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Introduction

Traditional Style Transfer

Given a set of 2D calibrated images, and a 2D style image, generate a 3D stylized radiance field.











Previous Work & Limitations

- Most approaches [1-4], focus on stylizing entire scenes
 - Usually 2 stages:
 - Train a photo-realistic radiance field
 - Fine-tune the 3D scene representation



- Object-specific style-transfer methods [3] perform instance based style transfer, and suffer from artifacts.
- These approaches do not incorporate language, and don't allow open-ended queries for object selection/style selection.



How can language help?

1. Object Selection

- User specifies object(s) to be stylized in the scene
 - Eg: Table, TV, Flower, Fern, ...
 - Allows semantic style transfer, instead of instance based

2. Style Specification

- User specifies style(s) using language
 - Eg: "in the style of Vincent Van Gogh", "floral print", ...

In this work, we focus on language driven object selection and plan to extend our work to allow language based style specification.

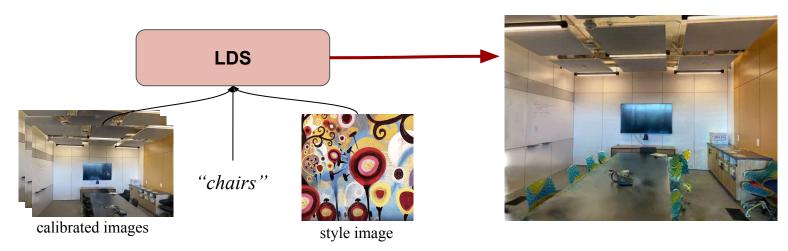


APPROACH

Overview

Inputs: Calibrated images of the 3D Scene, object query specified in natural language, and the style image.

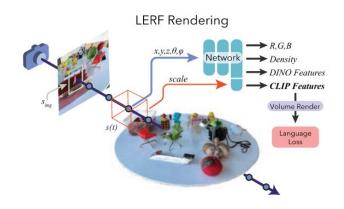
- 1. Train a photo-realistic radiance field using calibrated images
- 2. Generate semantic segmentation masks for given object
- 3. Fine-tune (style-transfer) only the mask area using VGG-based NNFM [4]





Approach 1: LERF (Language Embedded Radiance Fields) [5]

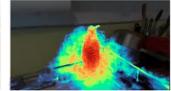
- Train a LERF model
 - a. Jointly optimize a language field along with a radiance field using CLIP+DINO
- Use the user specified object to query the trained LERF model and obtain the relevancy map
- 3. Convert this relevancy map to a **segmentation mask**, by thresholding
- 4. Fine-tune the trained LERF model with **NNFM** for style transfer







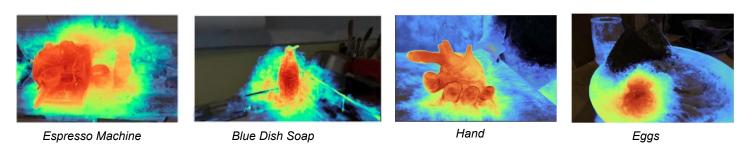






LERF Challenges

Noisy Relevancy Maps



- Expensive Compute
 - Training time: ~20min/epoch
 - Out of memory errors
 - Difficult to setup environment and dependencies



Approach 2: GroundedSAM (GroundingDINO[6] + SAM[7])

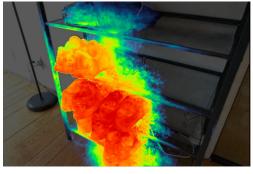
- 1. Train a radiance field on given calibrated images
- Generate object bounding boxes for given object query using GroundingDINO
- 3. Pass the bounding boxes to SAM to generate segmentation masks
- 4. Fine-tune the pretrained radiance field with masked NNFM for style transfer



Advantages over LERF

Accurate Segmentation Masks





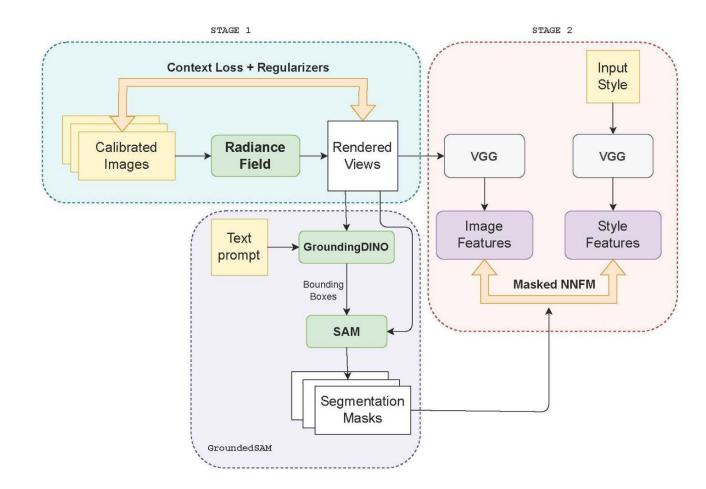


GroundedSAM Query: "shoes" **LERF**

- Reduced compute requirements
 ~45 minutes/experiment

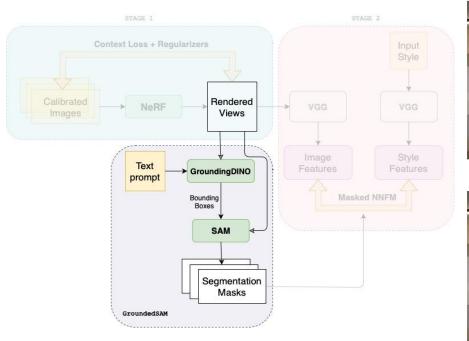


Pipeline





GroundedSAM



Original Image



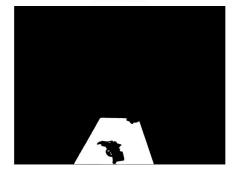
Grounding DINO Result + SAM Mask



Grounding DINO Result (Text: desk)

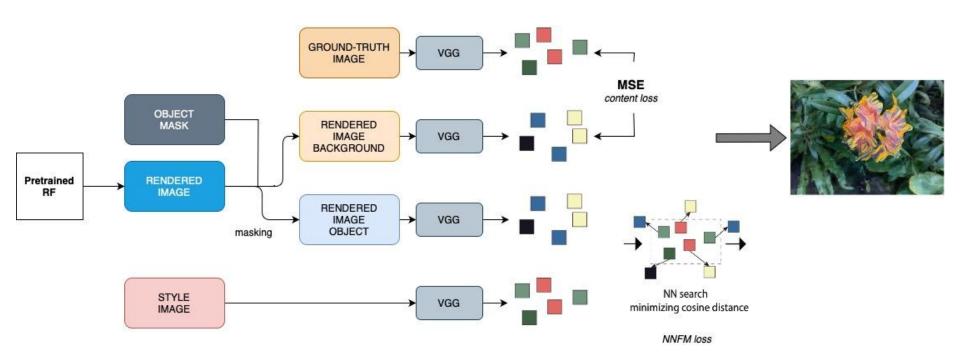


SAM Mask





Masked NNFM





Training



Pretraining





style

2 Epochs Prompt: "chairs"



10 Epochs Prompt: "chairs"

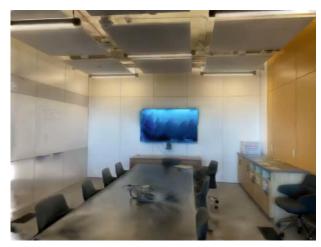






EXPERIMENTS

VGG Block







Block 0 Block 2 Block 4

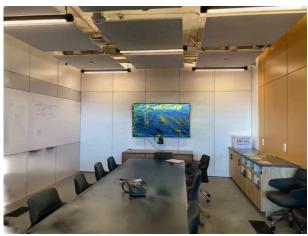
Prompt: "tv"

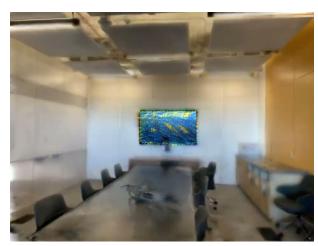
Style: Starry Night



Content Weight







1 1e-3 1e-6

Prompt: "tv"

Style: Starry Night



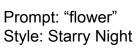
Qualitative Results (Different Styles)













Prompt: "flower"
Style: Abstract painting



Prompt: "flower" Style: Landscape



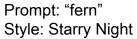
Qualitative Results (Different Styles)













Prompt: "fern"
Style: Abstract painting



Prompt: "fern"
Style: Landscape



Qualitative Results (Different Text Prompts)





Prompt: "desk" Style: Starry Night Prompt: "chairs"
Style: Starry Night



Qualitative Results (Different Prompts, Styles)



Prompt: "castle" Style: Starry Night





Prompt: "fortress" Style: Landscape





Qualitative Results (A Failure Exp)



Prompt: "dinosaur" Style: Starry Night



Prompt: "dinosaur"
Grounded SAM Result

Limitations & Future Work

Our work inherits limitations of GroundingDINO, SAM.

- SAM segmentations are guided by DINO bounding boxes, and not the input query
- With different views, bounding boxes have different scores -> different boxes to SAM
 - may lead to noisy mask and style transfer

We plan to extend our work to incorporate

- Stylizing multiple objects
- Stylizing multiple instances of same object with different styles
- **StyleAnything**: Language based style specification
 - Text conditioned style generation using stable diffusion



Q/A

THANK YOU

Outline

- Introduction & Problem Statement
- Previous work & limitations
- Approach
 - Overview
 - Approach 1: LERF
 - Challenges
 - Approach 2: GroundingDINO + SAM
 - Advantages
 - Final Pipeline
 - NeRF Pretraining
 - GroundingDINO + SAM
 - Style Transfer: VGG + NNFM

- Experiments
 - Content Weight
 - VGG-Block
 - Epochs
- Qualitative Results
- Future Work



Conclusions

Our method lies in the application of masked NNFM loss, enabling a more controllable style transfer;

Our method effectively achieves style transfer on both semantic and instance level, successfully applying distinct style(s) to multiple object(s) within a single scene.

(copied from ICCV)



Previous Work

Perform 3D stylization on point clouds or meshes are sensitive to **geometric reconstruction errors** for complex real-world scenes;

Commonly used **Gram matrix-based loss** tends to produce blurry results without faithful brushstrokes; (these two above copied from ARF)

Methods differ in the way they fine-tune or modify the 3D scene representation. Some works utilize a separate hyper networkwhile others alter the implicit representations themselves.

Focus on **whole-scene** stylization, be it through image or text modalities.; (these two above copied from S2RF)



Motivations

Enable language based object selection for stylization

TODO: Why GroundedSAM may performs better in this specified segmentation subtask?

In the realm of 3D scene stylization, we need to address **spatial consistency** challenge(intro to the NNFM Loss);

Constraint the style transfer to a **specified object** is challenging and active for research.



Approach 1:Using LERF

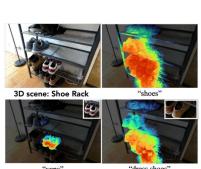


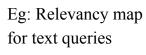
LERF

- 1.Train a LERF model
- (I.e. jointly optimize a language field along with a radiance field using CLIP+DINO supervision)
- 2.Use the user specified object to query the trained LERF model and obtain the relevancy map
- 3. Convert this relevancy map to a segmentation mask, by thresholding
- 4. Fine-tune the trained LERF model with Nearest

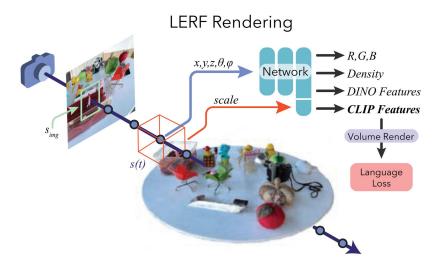
Neighbor Feature Matching(NNFM) loss for

style transfer









Issues

Generated relevancy maps are very noisy

Example: Like CLIP, language queries from LERF often exhibit "bag-of-words" behavior

(i.e., "not red" is similar to "red") and struggles to capture spatial relationships between objects.(copied from LERF paper)

Efficiency on our machines: **Long training times** (2 hours per experiment) + **low GPU memory**(hard to implement the best version "lerf", can only implement the small-scale version "lerf-lite")



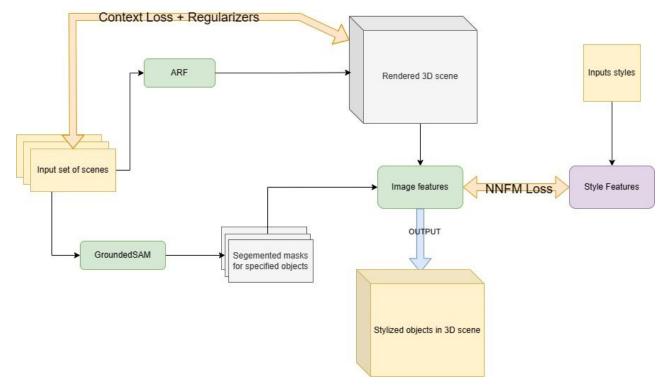
Approach 2:Using ARF with GroundedSAM (Now we used)



Pipeline

TODO: if any fault, can open/modify through draw.io (drawio.com) (regularizer should be DINO?)

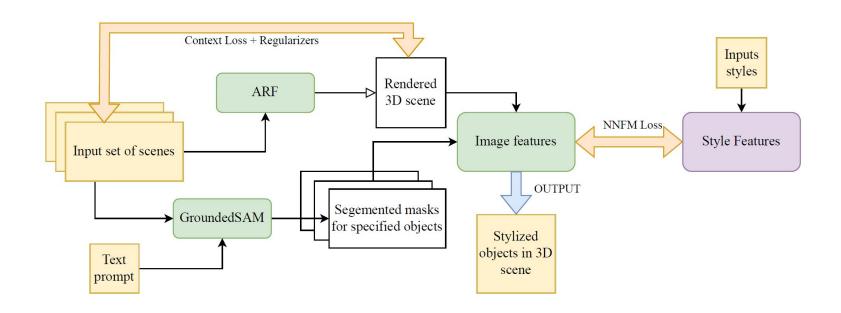
Shared link: Language-based Object Selection for 3D Stylization.drawio





Pipeline

I draw a new pipeline here (Jingmin) . See share drive here





Artistic Radiance Fields(ARF)

Use the user specified object query with GroundedSAM to generate the segmentation mask

Unlike a Gram matrix describing global feature statistics across the entire image, NN feature matching focuses on local image descriptions, better capturing distinctive local details.

VGG feature-based content loss(if used): balances stylization and content preservation, improves the color match between our final renderings and the input style;



Stylized NeRF

Fine-tune the pretrained NeRF model with NNFM for style transfer



Improvements

Accurate segmentation masks (show comparison between LERF and DINO+SAM)

Memory-friendly model + lower training time (~45 minutes per experiment)

NNFM Loss



Experiments & Qualitative Results

Experiment

VGG Block Ablation

Content weight ablation

Epoch-wise training progress



Experiment

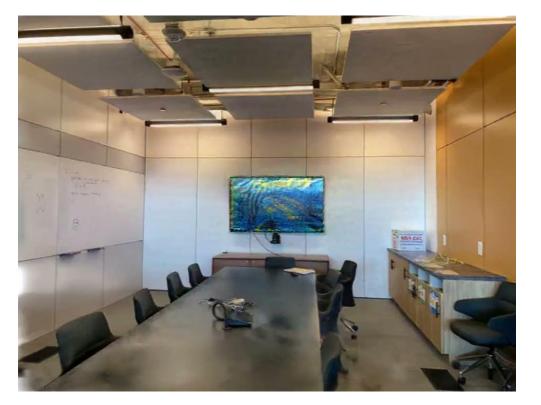
Content weight

Show comparison between different content weight for stylization

1, 1e-1, 1e-2, 1e-3, 1e-5

Write some observations

Dataset: room, Style image: Starry. Text prompt: "tv".





Different text prompt to model: "table" and "chair".







Different style init with same text prompt "tv".







Epochs

MSE_NUM_EPOCHS & NNFM_N_EPOCHS



Conclusions



Future Works

Encompass a <u>broader range of scenes</u>, including 360-degree environments and scenes with an increased number of objects.

Conduct more <u>quantitative evaluations</u> to thoroughly assess the effectiveness of our method.

(copied from ICCV)

